Environmental Protection Agency

Dynamometer Shaft Encoder Calibration Procedure

This procedure is written for the Environmental Protection Agency, National Vehicle and Fuel Emissions Laboratory (NVFEL) internal use. The use of specific brand names by NVFEL in this procedure are for reference only and are not an endorsement of those products. This document may be used for guidance by other laboratories.

NVFEL Reference Number

035A

Implementation Approval

Original Procedure Authorized by EPCN #268 on 10-05-2000

Revision Description

(1) 09-18-2001 The purpose of this change is to update the Group Responsible name per EPCN #316

Table of Contents

1.	Purpose	3
2.	Test Procedure	3
3.	Acceptance Criteria	14
	<u>Figures</u>	
Figure 1	Lock-out Main Switch	3
Figure 2	Disengaged Drive shaft	4
Figure 3	Calibrate Screen	4
Figure 4	Dyno Lockdown Fixture	5
Figure 5	Shaft Calibration Arm	5
Figure 6	Signal Display Screen	6
Figure 7	Setpoint Editor	7
Figure 8	Direction Arrow	7
Figure 9	Cal Plot for tqSHAFT	12
Figure 10	Review History Screen	12

1. Purpose

The purpose of this procedure is to document the steps required to perform the dynamometer shaft encoder calibration for PNGV cells.

2. Test Procedure

Go to the mezzanine above the test cell and turn off, lock, and tag out the main switch for the Meidensha dynamometer. See Figure 1.

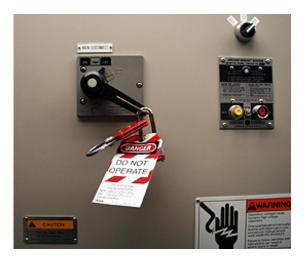


Figure 1 Lock-out Main Switch

- Press E Stop, the mechanical red emergency button.
- Ensure that the drive shaft is disconnected. If it is in place, remove the four bolts holding the cover in place, and then remove the cover plate.

In some cells, you can only remove 2 bolts, and then the cover can be raised while it remains attached on the one side.

Remove the 4 bolts connecting the drive shaft mounting flange to the dynamometer.

Use a pry-bar to disengage the drive shaft from its seat, so that it is not touching the dynamometer shaft. See Figure 2. Unbolt the drive shaft enclosure from the bed plate and slide away from the dyno hub.

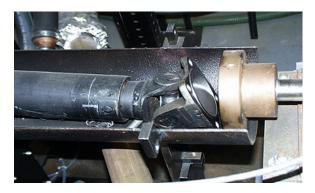


Figure 2
Disengaged Drive shaft

- If the PowerTek VX-In Engine controller computers and monitor are not turned on, follow WP 031 "PNGV Start VX-In" for the startup procedure.
- Open the "Displays" toolbar on the controller monitor and select "Special" then select "Calibrate".
- On the "Calibrate" screen, scroll up or down the "Channel Names" until "tqSHAFT" appears. See Figure 3. Double click on "tqSHAFT".

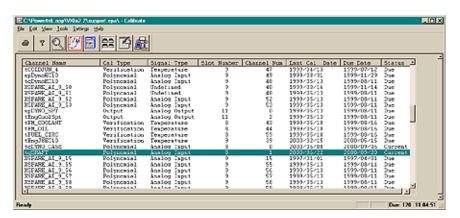


Figure 3 Calibrate Screen

"Operator ID" prompt will appear. Enter the operator ID and press "OK". Verify that the channel name is "tqSHAFT" The "Signal Display" screen will appear.

- Observe the "Raw Value" on the "Signal Display" screen. Record for later use.
- In the test cell, attach the dyno lock down fixture to the back of the dynamometer shaft to prevent shaft rotation. Attach two bolts to the hub and adjust the threaded rods. See Figure 4.



Figure 4 Dyno Lockdown Fixture

Attach the shaft calibration arm to the dyno drive hub with four bolts. See Figure 5.

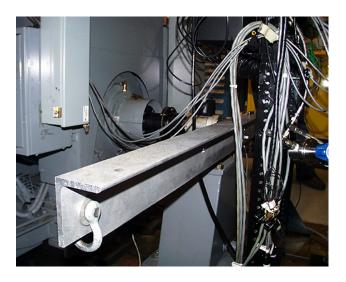


Figure 5
Shaft Calibration Arm

While observing the level on the top of the calibration arm, adjust the threaded rods on the fixture until the calibration arm is level.

Go to the control room. Observe the "Raw Value" on the Signal Display Screen. Verify that the "Raw Value" with the bar and "Raw Value" recorded in Step 109 agree to within 0.2 % of full range.

If it is within tolerance, select the field area for "Polynomial Order" by double-clicking on it and type in '3'. See Figure 6.

If it is not within tolerance, remove the shaft calibration arm and go to Step 110. If, after a second attempt, it is not within tolerance, notify the senior technician.

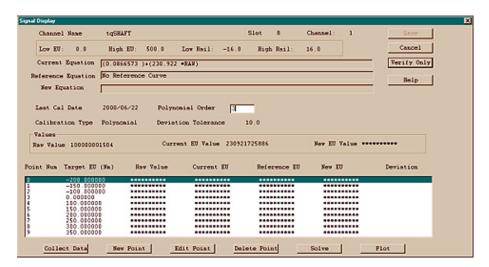


Figure 6 Signal Display Screen

In the bottom panel of the "Signal Display" screen, verify that "Target EU" 0.000000 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".

If the Target EU 0.000000 is not listed on the Signal Display screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear. See Figure 7.

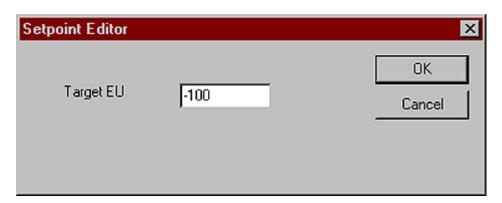


Figure 7
Setpoint Editor

Select the entry window for Target EU by clicking the mouse on it. Then type in "0.00" and click on "OK". When the "Signal Display" screen appears, highlight Target EU "0.000000" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

In preparation for adding weights on the arms, the determination of positive and negative changes relies on the direction of the arrow point on the drive shaft mount. The arrow points to the positive side. See Figure 8.



Figure 8
Direction Arrow

In the cell, attach the hang basket to the negative side arm of the drive shaft. The basket represents 100 Newton-meters. Once attached, tap on it to remove hysteresis.

- In the bottom panel of the "Signal Display" screen, verify that Target EU "-100" is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU -100 is not listed on the Signal Display screen, click on "New Point" button. The Setpoint Editor for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "-100" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "-100" and then click on the "Collect Data" button. A raw value will appear next to the "Target EU".

- In the cell, add a second weight which represents 100 Newton-meters to the hang basket for a total of -200 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that Target EU '-200' appears.

If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".

If the Target EU -200 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "-200" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "-200" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

- In the cell, add a third weight which represents 100 Newton-meters to the hang basket for a total of -300 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" -300 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the "Target EU" -300 is not listed on the "Signal Display" screen, click on the "New Point" button. The "Setpoint Editor" window for "Target EU" will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "-300" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "-300" and then click on the "Collect Data" button. A raw value will appear nest to the "Target EU".

- In the cell, add two more weights that represent 100 Newton-meters each and a weight that represents 50 Newton-meters to the hang basket for a total of -550 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" -550 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU -550 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "-550" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "-550" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

Begin removing the weights, one by one, in the order they were added and check the raw value with each removal. Each time the weight is detached, tap on the basket to remove hysteresis.

On the screen, check the raw value with each removal. The raw value should match the current EU value for each weight within \pm 1% of the total value. Once all the weights are removed from the negative side, repeat the calibration process on the positive side.

- In the cell, attach the hang basket to the negative side arm of the drive shaft. The basket represents 100 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" 100 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU 100 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "100" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "100" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

In the cell add a second weight which represents 100 Newton-meters to the hang basket for a total of 200 Newton-meters. Once attached, tap on it to remove hysteresis.

- In the bottom panel of the "Signal Display" screen, verify that "Target EU" 200 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU 200 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "200" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "200" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

- In the cell, add a third weight which represents 100 Newton-meters to the hang basket for a total of 300 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" 300 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU 300 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "300" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "300" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

- In the cell, add a fourth weight which represents 100 Newton-meters to the hang basket for a total of 400 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" 400 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU 400 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "400" and click on "OK". When the "Signal Display" screen appears, highlight Target EU "400" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

035A	Dynamometer Shaft Encoder Calibration Procedure	Page 11 of 1	
141	In the cell, add another weight that represents 100 Newton-meters and a weight that represents 50 Newton-meters to the hang basket for a total of 550 Newton-meters. Once attached, tap on it to remove hysteresis.		
142	In the bottom panel of the "Signal Display" screen, verify hat "Target EU" 550 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".		
143	If the Target EU 550 is not listed on the "Signal Display" screen, cli Point" button. The "Setpoint Editor" window for Target EU will ap		
	Select the entry window for Target EU by clicking the mouse on it. "550" and click on "OK".	Then type in	
	When the "Signal Display" screen appears, highlight Target EU "55 click on the "Collect Data" button. A raw value will appear next to		
144	Begin removing the weights, one by one, in the order they were added and check the raw value with each removal. Each time the weight is detached, tap on the		

On the screen, check the raw value with each removal. The raw value should match

Once all the positive weights are removed, click on the "Solve" button. Verify that

the current EU value for each weight within \pm 1% of the total value.

basket to remove hysteresis.

Click on the "Plot" button.

you have new EU numbers in the panel.

145

146

14

The "Cal Plot for tqSHAFT" appears. See Figure 9. Verify that the plot forms a straight line.

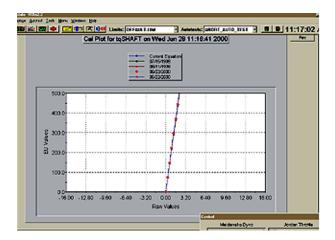


Figure 9 Cal Plot for tqSHAFT

- In the upper right corner of the "CalPlot" display, press the "Print" button.
- 149 Click on the "OK" button of the Cal Plot display to return to the Signal Display screen.
- 150 Click on "Save" button of the Signal Display to return to the "Calibrate" screen.
- On the "Calibrate" screen, select "Tools" menu, and from the menu select "View Calibration History".
- Ensure that "tqSHAFT" appears on the "Review History" screen in the "Channel Name" box. See Figure 10.

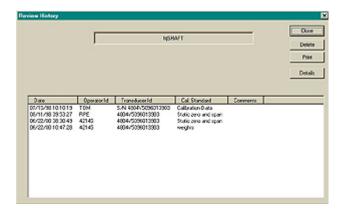


Figure 10 Review History Screen

035A	Dynamometer Shaft Encoder Calibration Procedure Page 13 of 14
153	From the list in the bottom display, highlight the calibration that was just performed.
154	Click on the "Print" button in the upper right hand corner.
155	Click "OK" when the "Print" screen appears.
156	A calibration report will be printed. On the "Review History" screen, click "Close".
157	On the "Calibrate" screen, click on the "File" menu and select "EXIT".
158	In the cell, remove the calibration arms and hold down fixture for the dyno, and return them with the bolts to their storage location.
159	Re-attach the drive shaft to dynamometer by loosely threading the bolts to the mounting flange.
160	Tighten one bolt with a torque wrench to 65 ftlb Use a pry bar to rotate the drive shaft.
161	Tighten with a torque wrench, the bolt opposite the first one to 65 ft-lb. Use a pry bar to rotate the drive shaft.
162	Use the torque wrench to tighten the third bolt to 65 ft-lb. Use a pry bar to rotate the drive shaft.
163	Tighten the remaining bolt with the torque wrench to 65 ft-lb.
164	Repeat the procedure used in Steps 160-162 to tighten the four bolts with a torque wrench to 75 ft-lb.
165	Move the drive shaft to its original position.
166	Replace the drive shaft cover by securing either the removed four or the removed two bolts back to it.
167	Shut down the computer by following the steps in WP 032 "PNGV Stop VX-In".
168	Staple the "Cal Plot for tqSHAFT" and "Calibration Summary" printouts together and place them in the "Dynamometer Calibrations Records" cabinet.

035A	Dynamometer Shaft Encoder Calibration Procedure	Page 14 of 14
00011	2 judinometer Suart Encoder Canstation 110ccdare	- "SO I ! UI I !

- Go to the mezzanine and remove the lock and lockout tag from the Meidensha dynamometer main switch. Turn on the power to the dynamometer.
- Turn the E Stop mechanical red emergency button until it releases.

3. Acceptance Criteria

- 3.1 The raw value must match the current EU value for each weight within \pm 1% of the total value.
- 3.3 The Cal Plot data visually forms a straight line.
- 3.4 The Cal Plot for tqSHAFT" and "Calibration Summary" printouts are filed in the "Dynamometer Calibrations Records" cabinet.
- 3.5 The four bolts to the mounting flange are tightened to 75 ft.-lb.